


```

[ kn# := kn# + 1 kv# := kv# + 1 " kv# := " kn# ]
E# := Equirep ( E# , a# , u# kn# )
[ kv# := kv# + 1 U# n# := v# n# V# kv# := v# n# ]
E# := Equirep ( E# , a# , v# n# )
"From here is solve then Rkadapt"
RK_F# ( v# ) := eval ( E# )
RK_D# ( t# , u# ) := [ str2num ( concat ( ts# , ":", num2str ( t# ) ) )
                      v# := al_nleqsolve ( I'# , RK_F# )
                      eval ( V# ) ]
Rkadapt ( str2num ( ic# ) , str2num ( to# ) , TF# , N# , RK_D# )

```

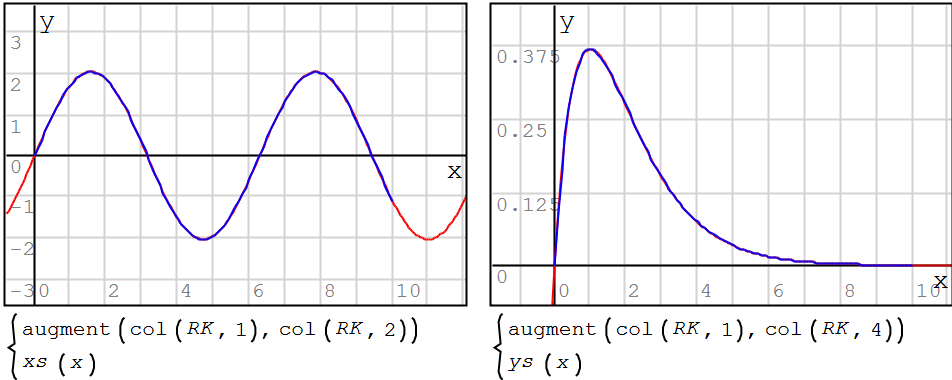
Example

DE System

$$DE := \begin{cases} y''(t) \cdot t - x(t) \cdot y(t) = -\frac{t \cdot (2 - t + 2 \cdot \sin(t))}{e^t} \\ x''(t) - \cos(4 \cdot t) \cdot y'(t) = -\frac{2 \cdot \sin(t) \cdot e^t + \cos(4 \cdot t) \cdot (1 - t)}{e^t} \\ x'(0) = 2 \\ y(0) = 0 \\ y'(0) = 1 \\ x(0) = 0 \end{cases}$$

$$RK := RKA \left(DE, \left\{ \begin{matrix} x(t) \\ y(t) \end{matrix} \right\}, \begin{bmatrix} 0 \\ -2 \end{bmatrix}, 10, 100 \right)$$

$$\begin{cases} xs(t) := 2 \cdot \sin(t) \\ ys(t) := t \cdot e^{-t} \end{cases}$$



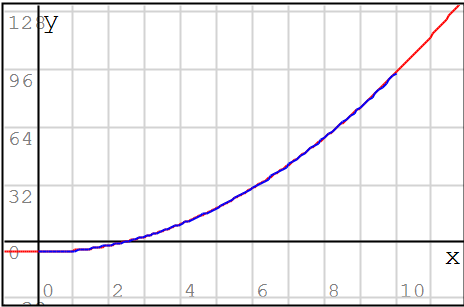
Example

DE System

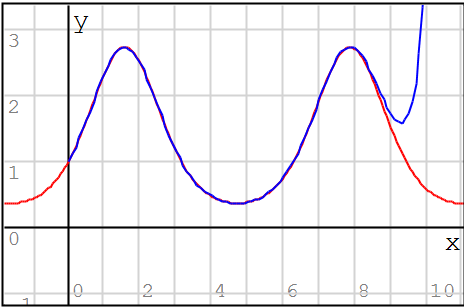
$$DE := \begin{cases} a''(t) \cdot b(t) - c(t) = \frac{4 \cdot (1 + e^{\sin(t)})}{2} - t^2 \\ b''(t) - t \cdot c'(t) = e^{\sin(t)} \cdot ((\cos(t))^2 - \sin(t)) - t^2 \\ c''(t) \cdot a''(t) - 3 \cdot b(t) = 2 - 3 \cdot e^{\sin(t)} \\ a'(0) = 0 \\ b(0) = 1 \\ b'(0) = 1 \\ c'(0) = 0 \\ a(0) = -6 \\ c(0) = -2 \end{cases}$$

$$RK := RKA \left(DE, \left\{ \begin{matrix} a(t) \\ b(t) \\ c(t) \end{matrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, 10, 100 \right\} \right)$$

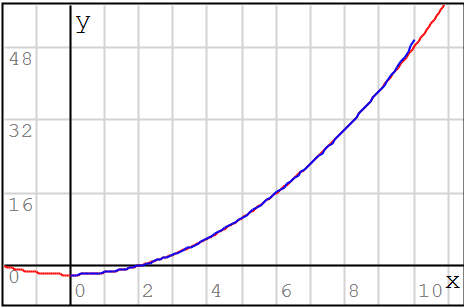
$$\begin{cases} xs(t) := t^2 - 6 \\ ys(t) := e^{\sin(t)} \\ zs(t) := 0.5 \cdot t^2 - 2 \end{cases}$$



$$\begin{cases} \text{augment}(\text{col}(RK, 1), \text{col}(RK, 2)) \\ xs(x) \end{cases}$$



$$\begin{cases} \text{augment}(\text{col}(RK, 1), \text{col}(RK, 4)) \\ ys(x) \end{cases}$$



$$\begin{cases} \text{augment}(\text{col}(RK, 1), \text{col}(RK, 6)) \\ zs(x) \end{cases}$$

Example

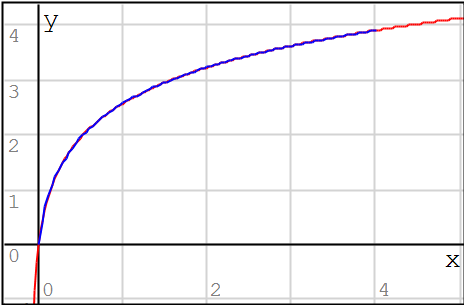
DE System

$$\alpha := 12$$

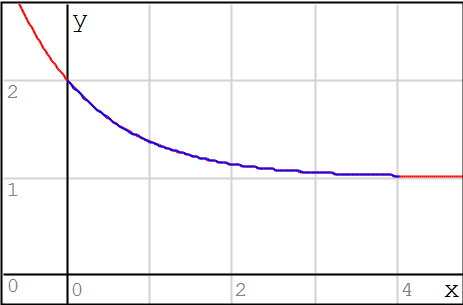
$$DE := \begin{cases} v''(\sigma) \cdot v(\sigma) - \sigma \cdot u(\sigma) = \frac{e^{\sigma} + 1 - \sigma \cdot \ln(1 + \alpha \cdot \sigma) \cdot e^{2 \cdot \sigma}}{e^{2 \cdot \sigma}} \\ u'(\sigma) \cdot v''(\sigma) + \cos(2 \cdot \sigma) = \frac{\alpha + \cos(2 \cdot \sigma) \cdot (1 + \alpha \cdot \sigma) \cdot e^{\sigma}}{(1 + \alpha \cdot \sigma) \cdot e^{\sigma}} \\ v(0) = 2 \\ v'(0) = -1 \\ u(0) = 0 \end{cases}$$

$$RK := RKA \left(DE, \left\{ \begin{matrix} u(\sigma) \\ v(\sigma)' \end{matrix}, \begin{bmatrix} \alpha \\ 1 \end{bmatrix}, 4, 100 \right\} \right)$$

$$\begin{cases} us(\sigma) := \ln(1 + \alpha \cdot \sigma) \\ vs(\sigma) := e^{-\sigma} + 1 \end{cases}$$



$$\begin{cases} \text{augment}(\text{col}(RK, 1), \text{col}(RK, 2)) \\ us(x) \end{cases}$$



$$\begin{cases} \text{augment}(\text{col}(RK, 1), \text{col}(RK, 3)) \\ vs(x) \end{cases}$$

Alvaro